

# Distributed Evaluation of Enhanced Path Queries

Dan C. Stefanescu, Alex Thomo

# Label setting vs. Label Correcting Algorithms

- Label setting algorithms: Use priority queue
  - E.g. Dijkstra's
  - When a node is labeled we know for sure that it's the best label, i.e. it will be the weight of the shortest path from the source to that node.
- Label correcting algorithms: Use FIFO queue
  - E.g. Pallotino's
  - When a node is labeled we don't know for sure that it's the best label, possibly we will improve it later.
  - **Appropriate to extend to distributed setting...**

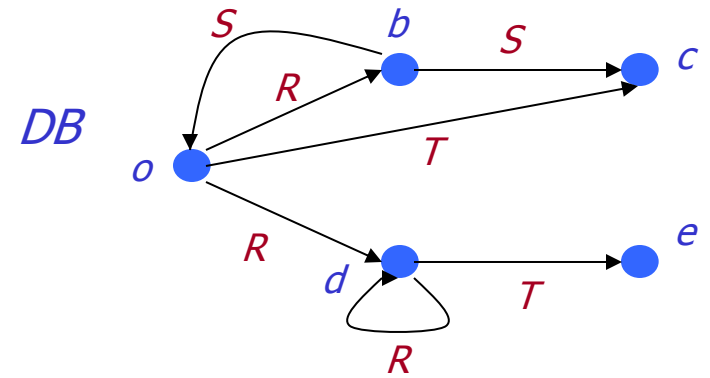
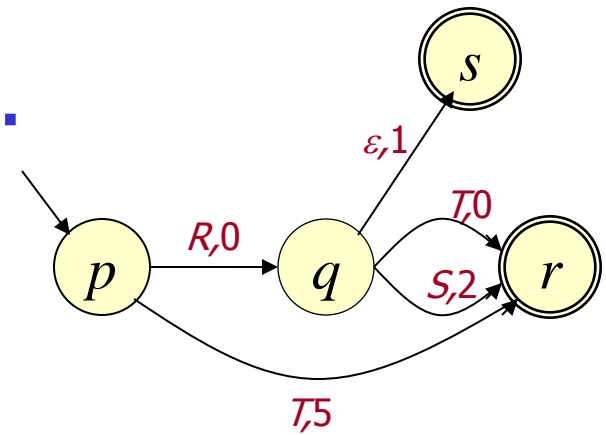
# Let's apply it...

We will build the green graph implicitly and lazily.

Along the way we will apply the shortest path general algorithm.

*Queue* :  $(o,p,0)$

*Object-State-Weight Table* : Here we store the "labeling"s of the green graph nodes.



# Let's apply it...

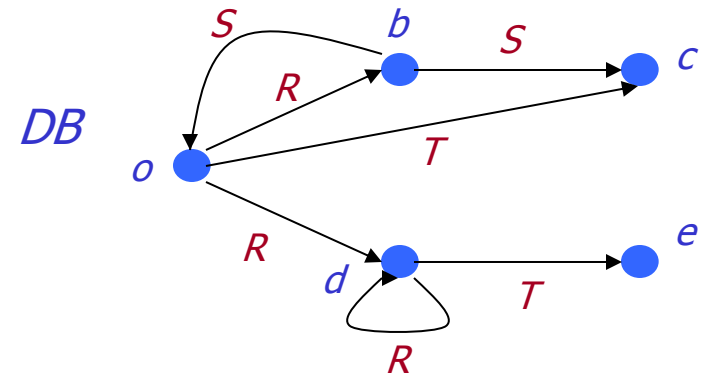
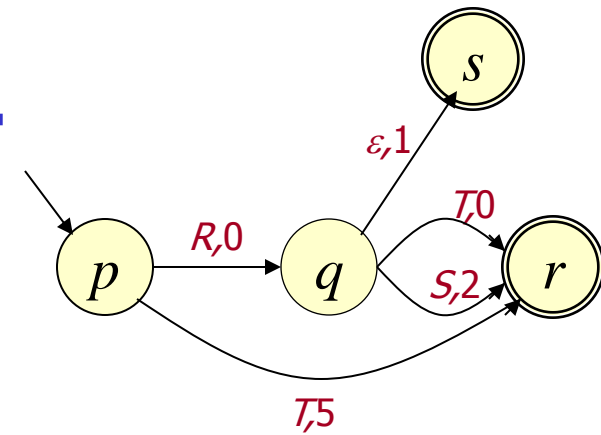
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*Queue* :  $(c,r,5)$   $(b,q,0)$   $(d,q,0)$

*Object-State-Weight Table* : Here we store the "labeling"s of the green graph nodes.

$(o,p,0)$



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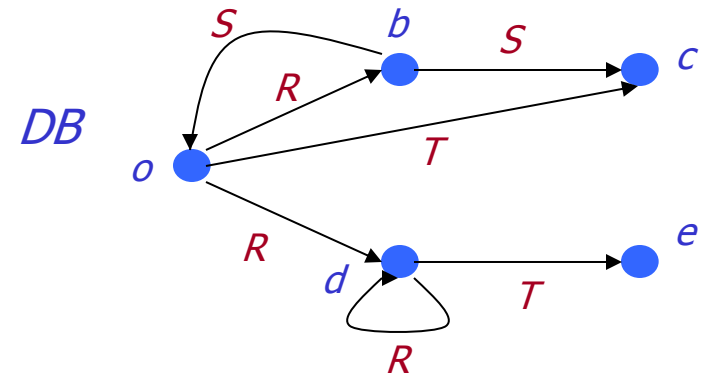
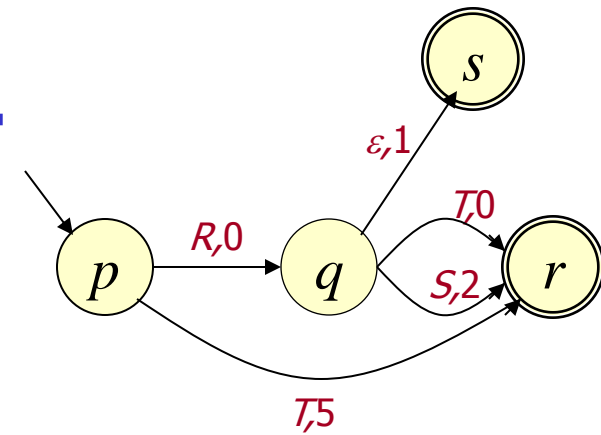
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$(o,p,0)$   $(c,r,5)$



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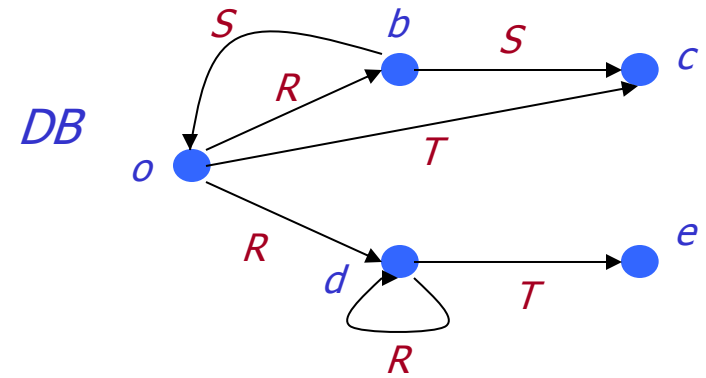
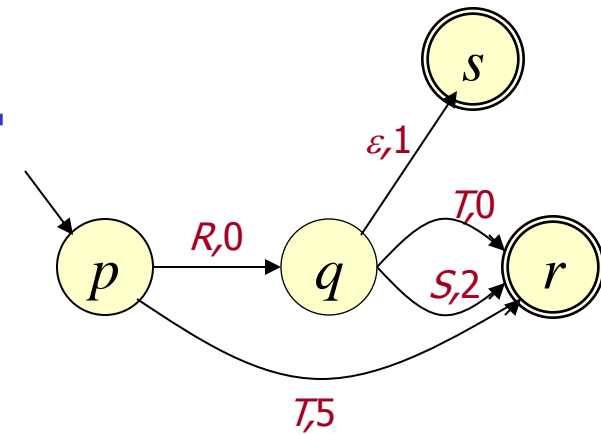
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*Queue* :  $(d,q,0)$   $(b,s,1)$   $(c,r,2)$

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$(o,p,0)$   $(c,r,5)$   $(b,q,0)$



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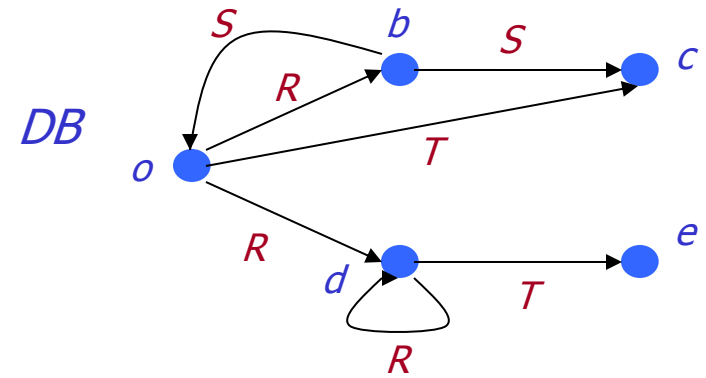
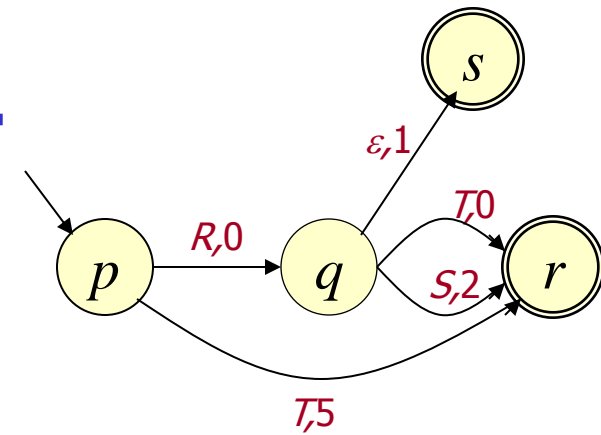
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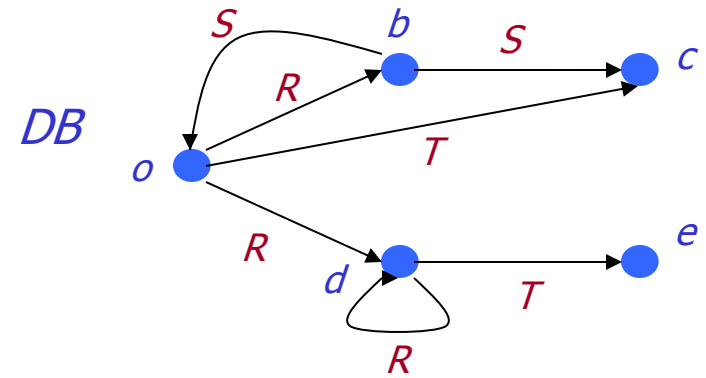
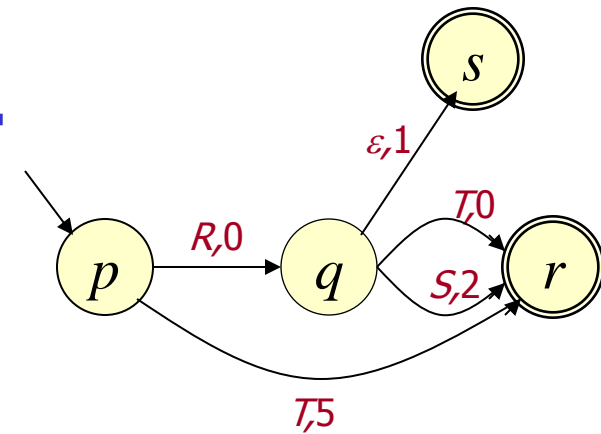
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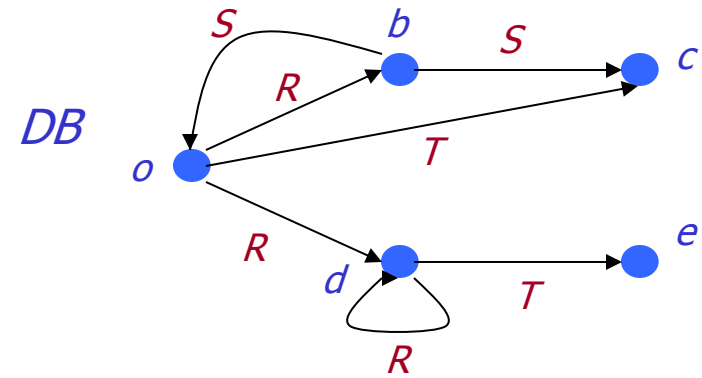
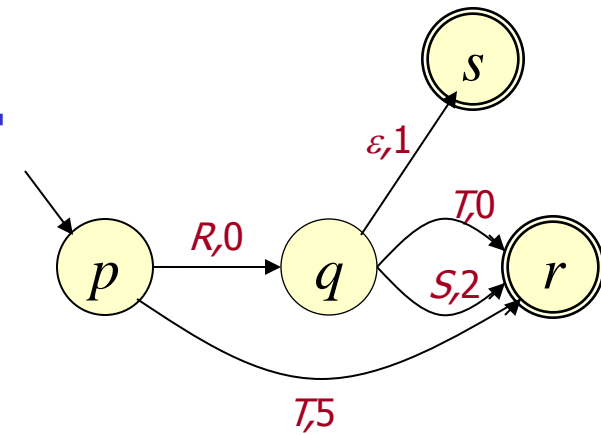
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$(o,p,0)$   $(c,r,2)$   $(b,q,0)$   $(d,q,0)$   $(b,s,1)$

...



# Distributed Algorithm

- The nodes are partitioned in different processors, which don't share memory.
- Communication is achieved through asynchronous message passing.

## Idea

- Partition the *Object-State-Weight* table among the processors
- When dequeuing see whether the corresponding object is in the local *Object-State-Weight* table.
  - If yes, proceed as previously
  - Otherwise pack the dequeued triple in a message and send it to the processor holding the real DB node.
- Terminate when the processing queues of all processors are empty and there is no message sent but not yet received.

# Distributed Algorithm

Suppose:

$o, d$  are in processor P1

$b, c, e$  are in processor P2

P1:

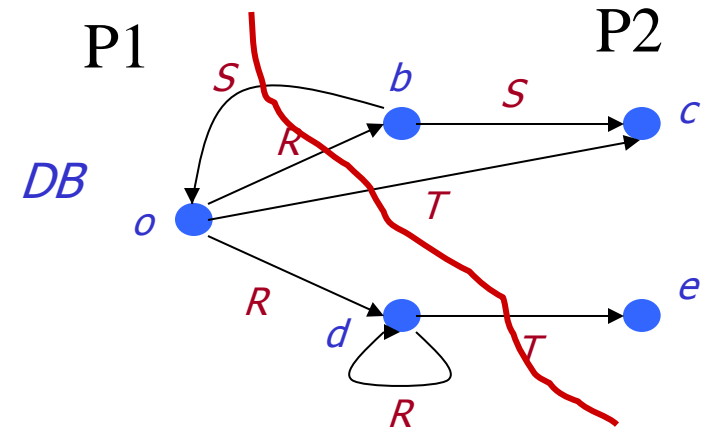
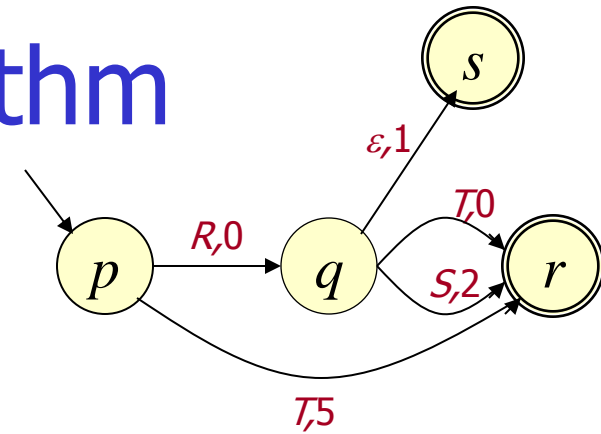
*Queue* :  $(o, p, 0)$

*Object-State-Weight Table* :

P2:

*Queue* :

*Object-State-Weight Table* :



# Distributed Algorithm

Suppose:

$o, d$  are in processor P1

$b, c, e$  are in processor P2

P1:

Queue :  $(c,r,5) (b,q,0) (d,q,0)$

Object-State-Weight Table :

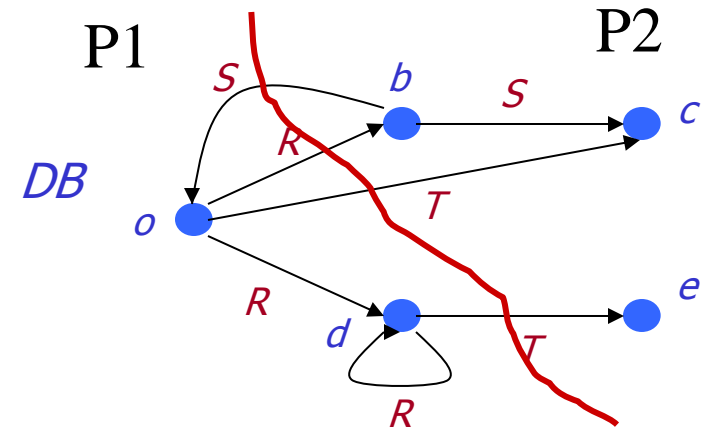
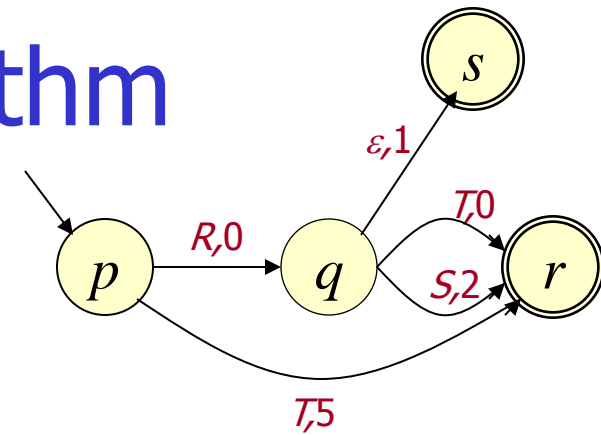
$(o,p,0)$

*message*  $(c,r,5)$

P2:

Queue :

Object-State-Weight Table :



# Distributed Algorithm

Suppose:

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P1:

Queue :  $(b, q, 0) (d, q, 0)$

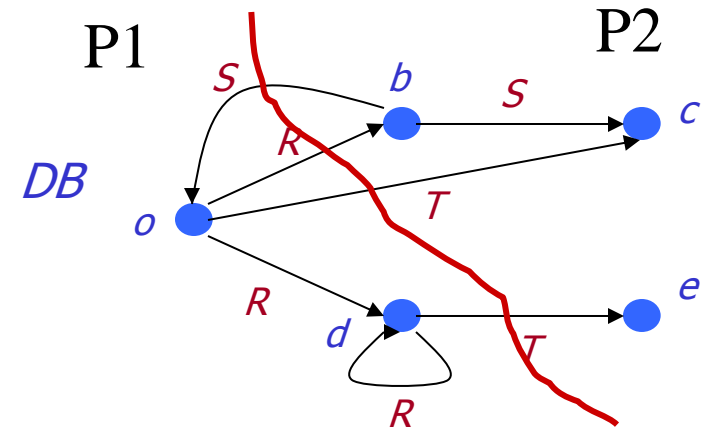
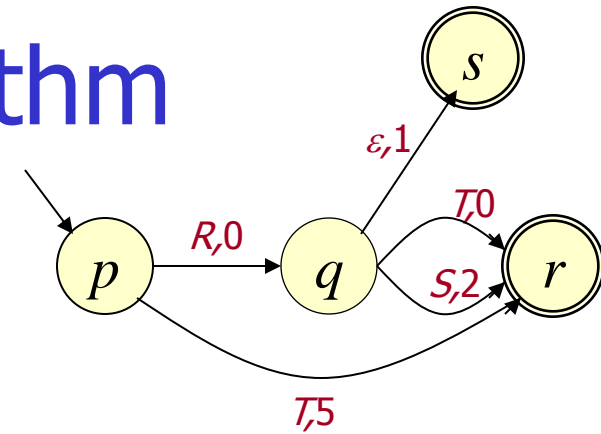
Object-State-Weight Table :

$(o, p, 0)$

P2:

Queue :  $(c, r, 5)$

Object-State-Weight Table :



# Distributed Algorithm

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P1:

Queue :  $(b,q,0) (d,q,0)$

Object-State-Weight Table :

$(o,p,0)$

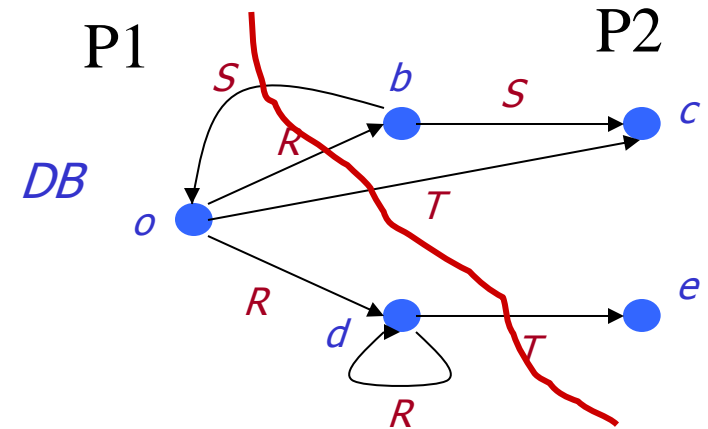
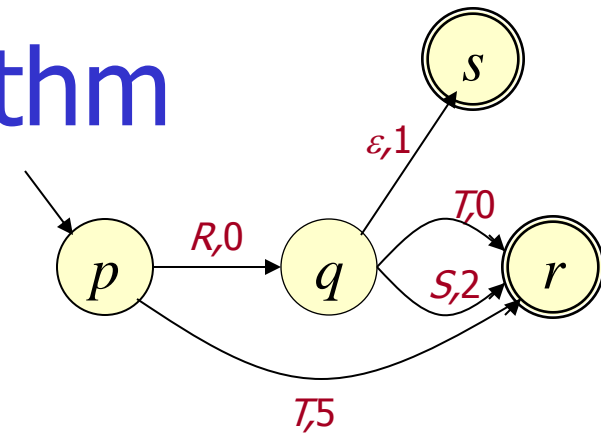
message  $(b,q,0)$

P2:

Queue :

Object-State-Weight Table :

$(c,r,5)$



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Object-State-Weight Table :

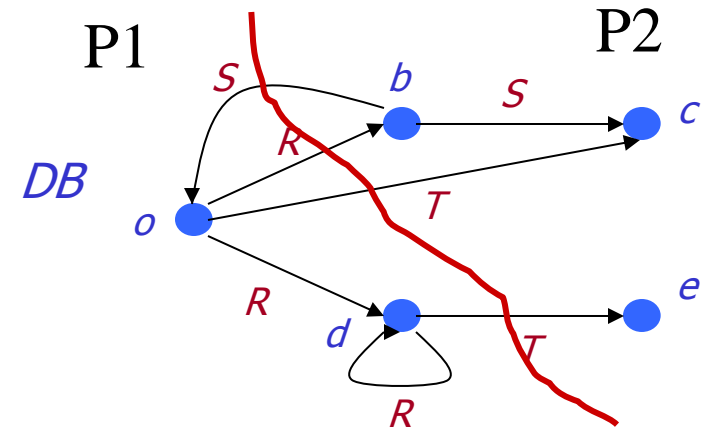
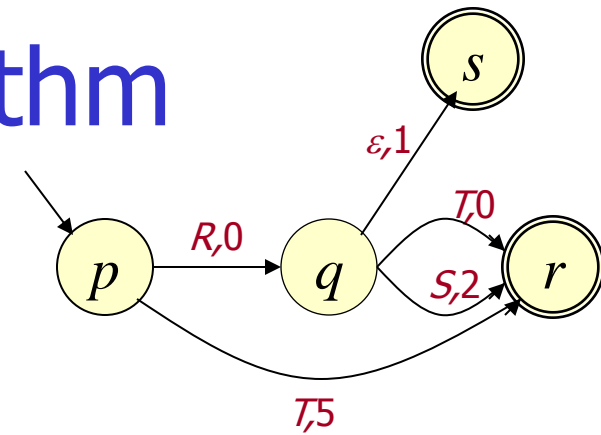
$(o, p, 0)$

P2:

Queue :  $(b, q, 0)$

Object-State-Weight Table :

$(c, r, 5)$



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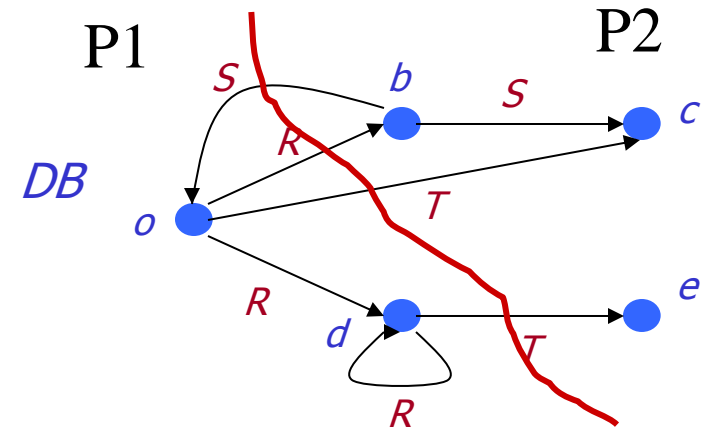
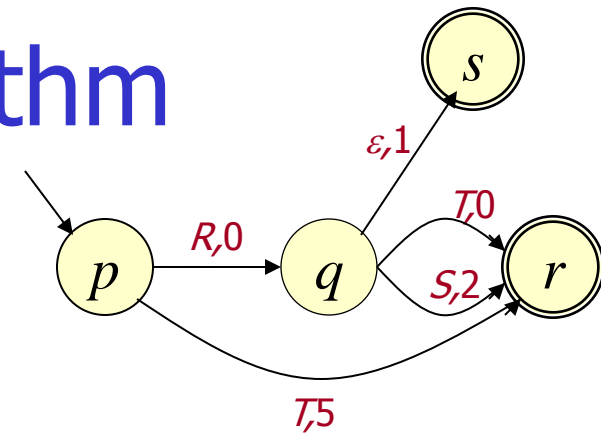
$(o, p, 0)$

P2:

Queue :  $(b, s, 1) (c, r, 2) (o, r, 2)$

Object-State-Weight Table :

$(c, r, 5) (b, q, 0)$





# Distributed Algorithm

Suppose:

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P1:

Queue :  $(d, q, 0)$

Object-State-Weight Table :

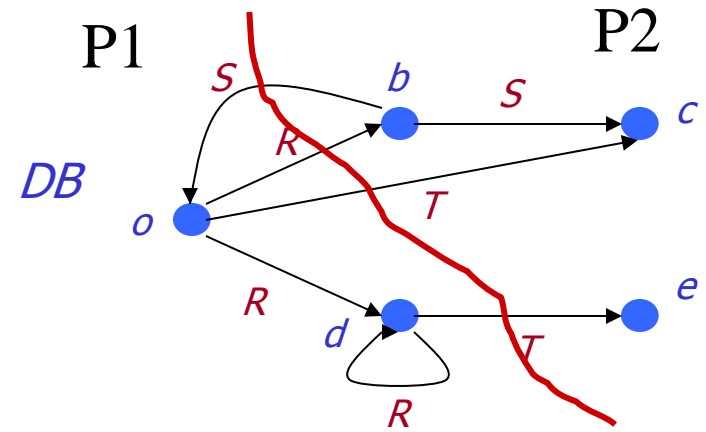
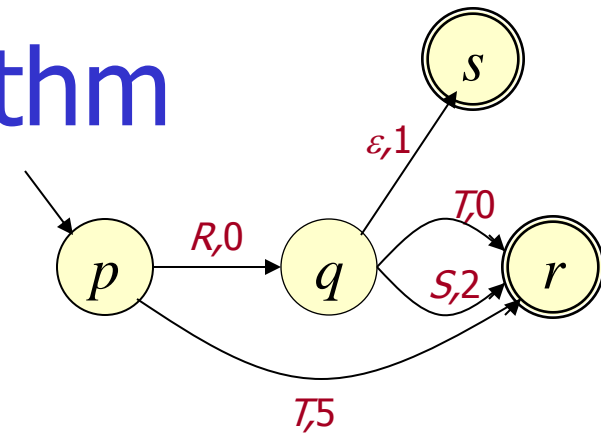
$(o, p, 0)$

P2:

Queue :  $(c, r, 2) (o, r, 2)$

Object-State-Weight Table :

$(c, r, 5) (b, q, 0) (b, s, 1)$



# Distributed Algorithm

Suppose:

$o, d$  are in processor P1

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*Queue* :  $(d,s,1) (e,r,0)$

*Object-State-Weight Table* :

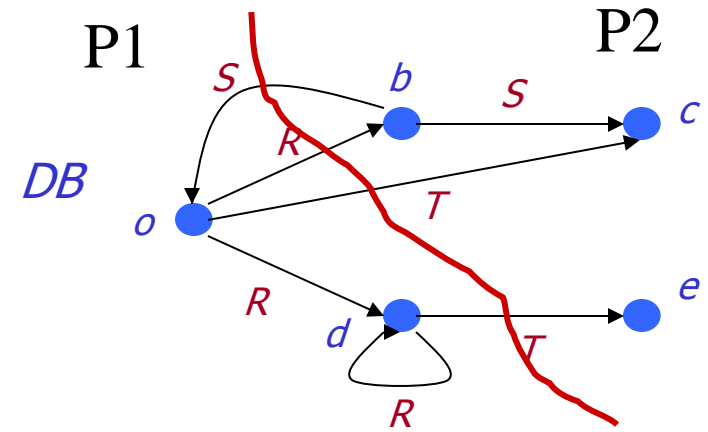
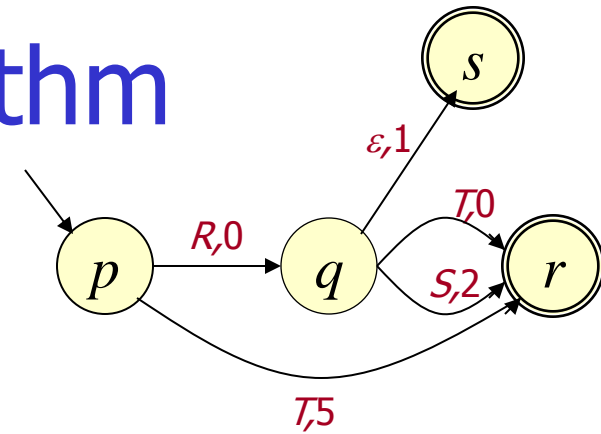
$(o,p,0) (d,q,0)$

P2:

*Queue* :  $(o,r,2)$

*Object-State-Weight Table* :

$(c,r,2) (b,q,0) (b,s,1)$

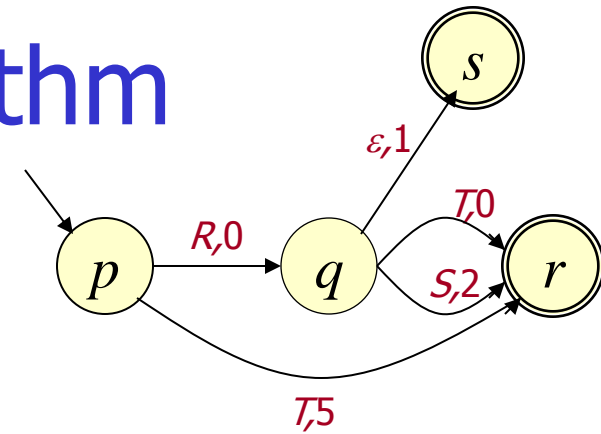


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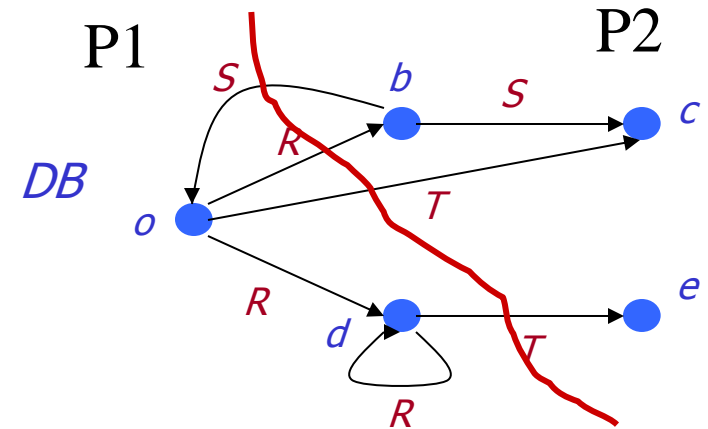
$(o,p,0)$   $(d,q,0)$   $(d,s,1)$

P2:

Queue :  $(o,r,2)$

Object-State-Weight Table :

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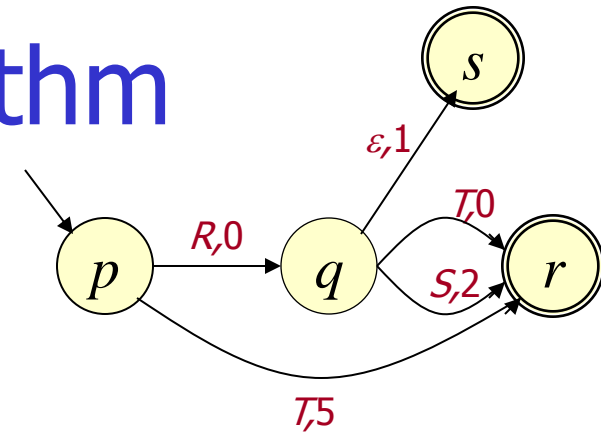


# Distributed Algorithm

Suppose:

$o, d$  are in processor P1

$b, c, e$  are in processor P2

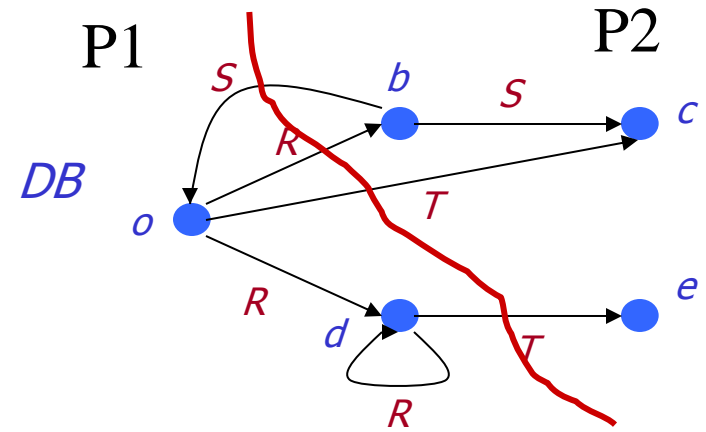


P1:  $\leftarrow$   
 Queue :  $(e,r,0)$

Object-State-Weight Table :  
 $(o,p,0) (d,q,0) (d,s,1)$   
*message*  $(o,r,2)$

P2:  
 Queue :  $(o,r,2)$

Object-State-Weight Table :  
 $(c,r,2) (b,q,0) (b,s,1)$

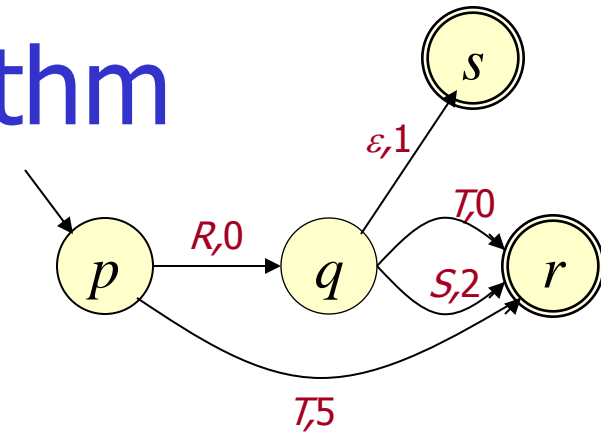


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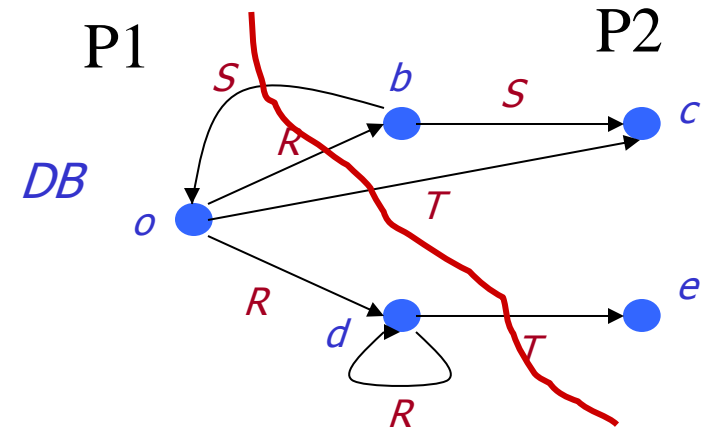
$(o,p,0)$   $(d,q,0)$   $(d,s,1)$

P2:

Queue :

Object-State-Weight Table :

$(c,r,2)$   $(b,q,0)$   $(b,s,1)$



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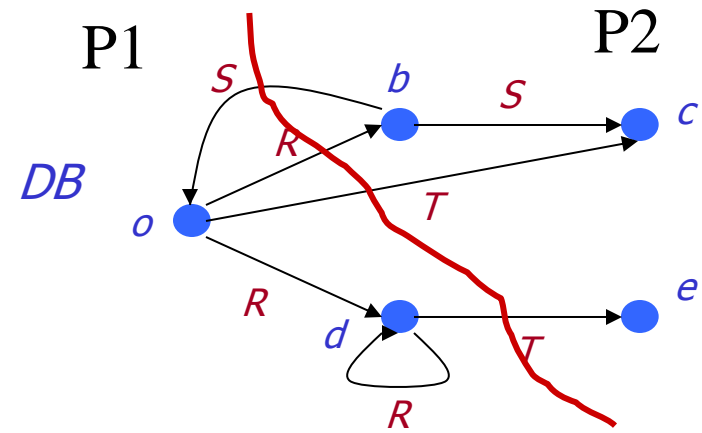
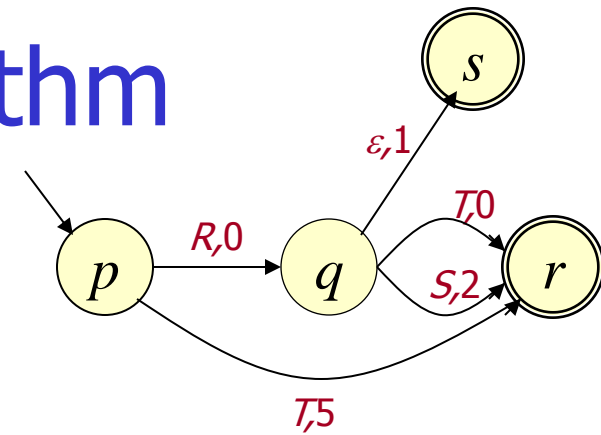
$(o, p, 0)$   $(d, q, 0)$   $(d, s, 1)$   $(o, r, 2)$

P2: ← *message*  $(e, r, 0)$

Queue :

Object-State-Weight Table :

$(c, r, 2)$   $(b, q, 0)$   $(b, s, 1)$



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Queue :

Object-State-Weight Table :

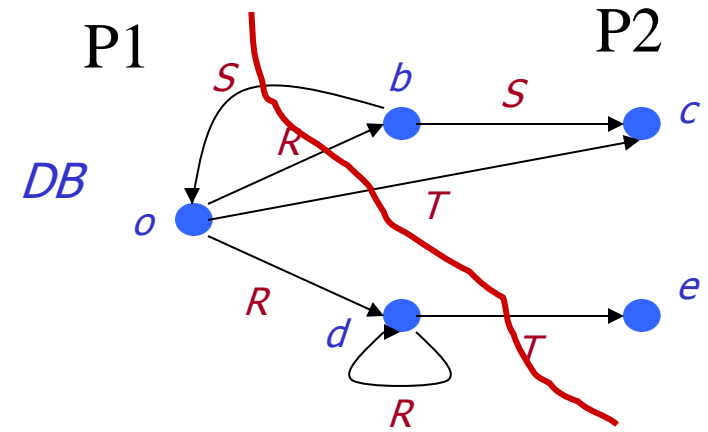
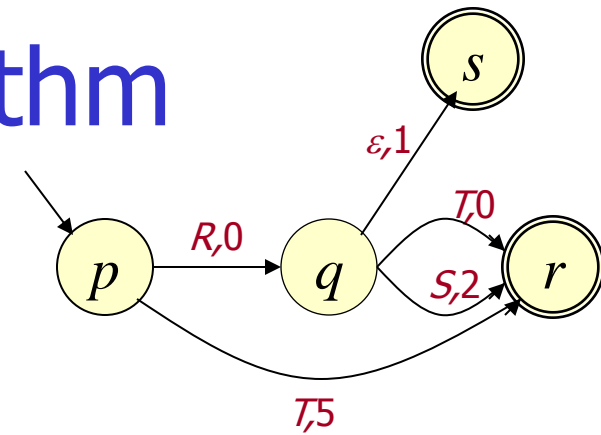
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P2:

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Object-State-Weight Table :

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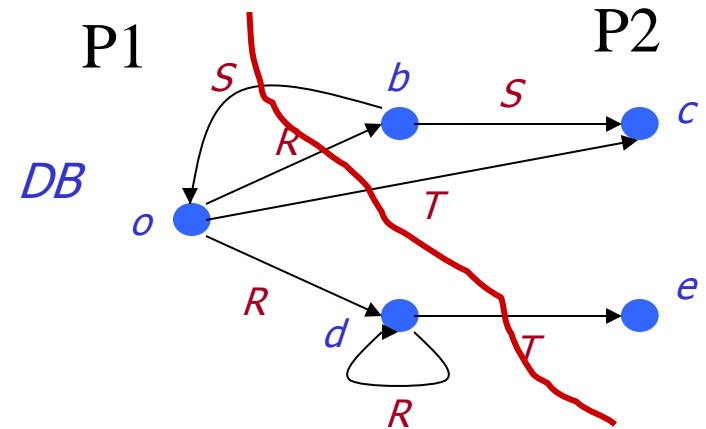
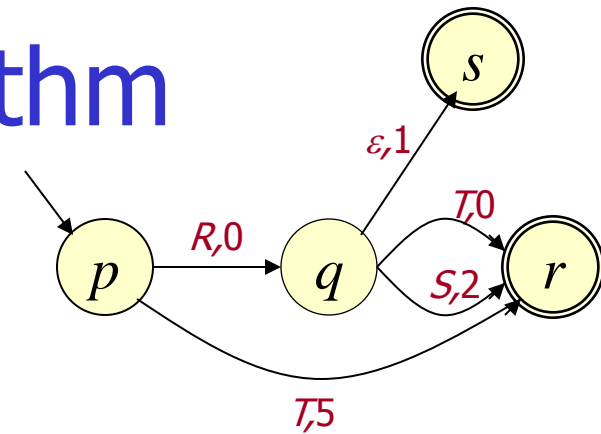
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P2:

Queue :

Object-State-Weight Table :

$(c,r,2)$   $(b,q,0)$   $(b,s,1)$   $(e,r,0)$





# References

- Dan C. Stefanescu, Alex Thomo. Enhanced Regular Path Queries on Semistructured Databases. EDBT Workshops 2006: 700-711
- Dan C. Stefanescu, Alex Thomo, Lida Thomo. Distributed evaluation of generalized path queries. SAC 2005: 610-616
- Gösta Grahne, Alex Thomo. Query Answering and Containment for Regular Path Queries under Distortions. FoIKS 2004: 98-115