

Boundedness of Regular Path Queries in Data Integration Systems

Gösta Grahne, Alex Thomo

Regular Path Queries

Useful for expressing **desired paths** to follow in graph DB's.

E.g.

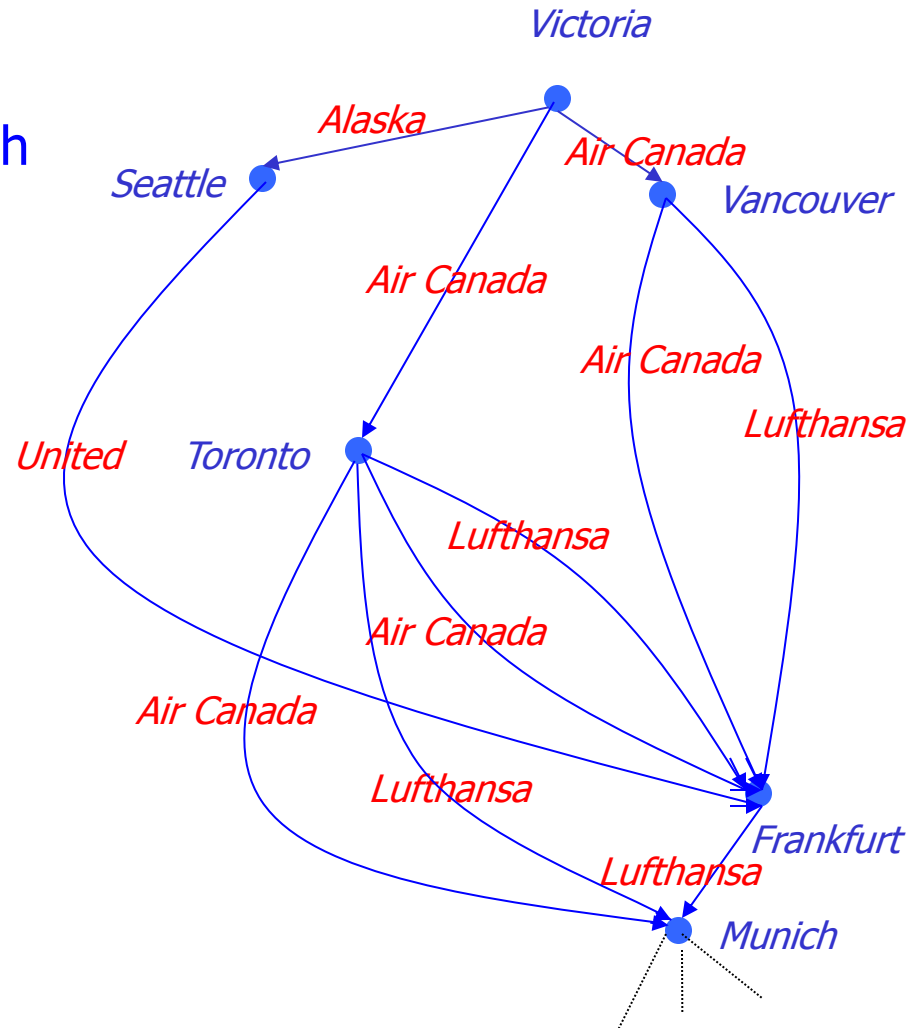
I want to go from **Victoria** to **Munich** taking **Air Canada** or **Lufthansa** or **United**.

Query:

$(\text{Air Canada} + \text{Lufthansa} + \text{United})^*$

Answer:

{ (Victoria, Vancouver),
(Victoria, Frankfurt),
(Victoria, Munich),
...
}



Data Sources

Suppose I have a not available the previous DB.
What I have is "data sources" (views)

V: (Air Canada+Lufthansa)*

Extension:

{(Victoria,Vancouver),
(Victoria,Frankfurt),
(Victoria,Munich), (Victoria,Hanover), ...}

LAV (local-as-view) data integration

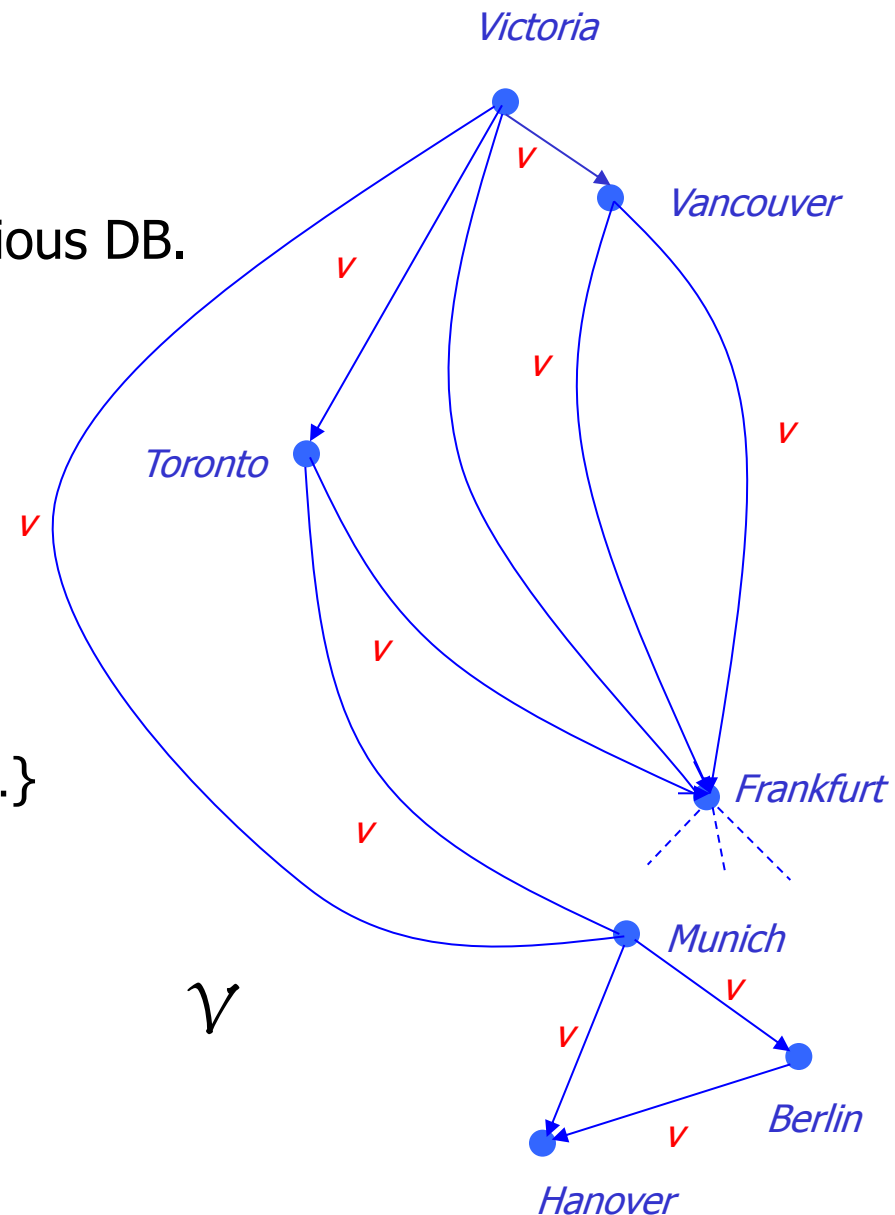
Global Schema:

$\Delta = \{\text{Air Canada, Lufthansa, United, BA, AA, Alaska, ...}\}$

Local Schema:

$\Omega = \{v, \dots\}$

User posses queries on the global schema



Query Answering

Q: (Air Canada+Lufthansa+United)*

V: (Air Canada+Lufthansa)*

Two approaches for answering queries:

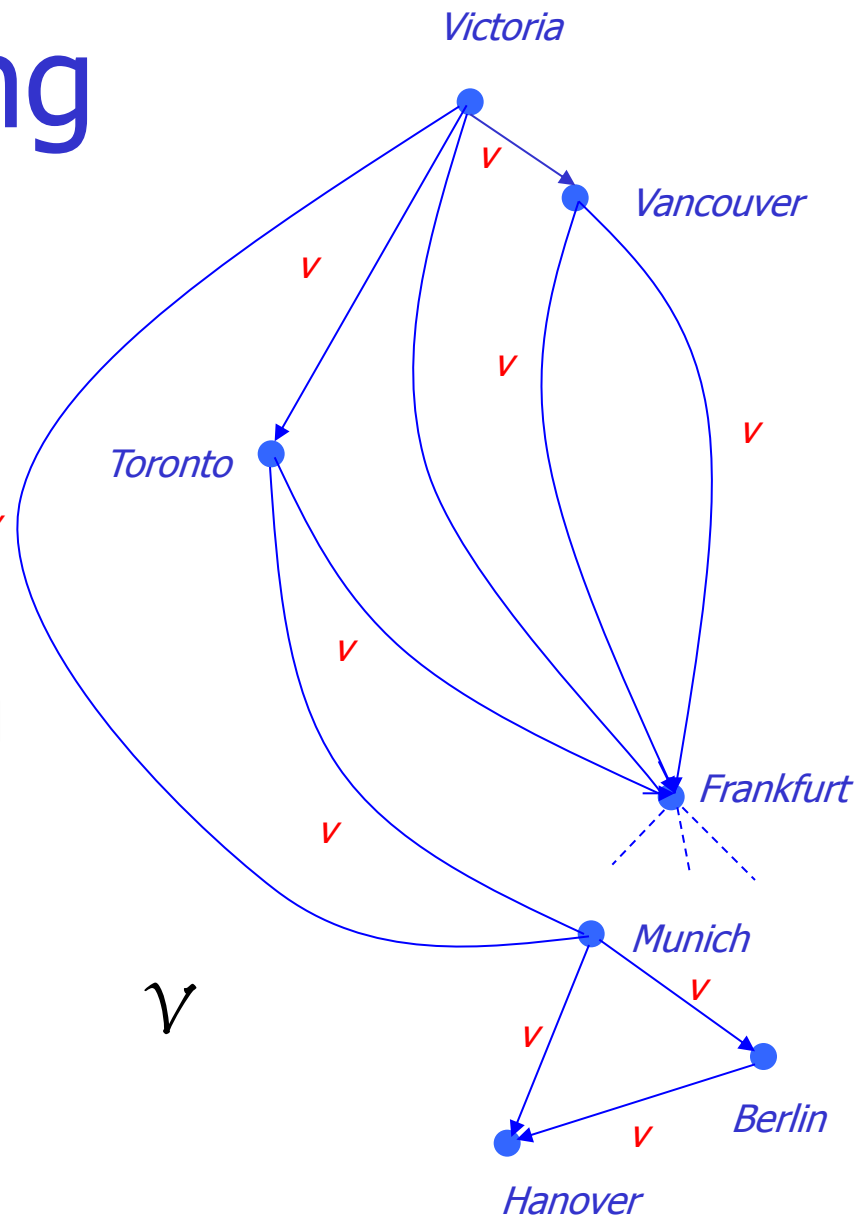
- Compute the **certain answer** (very expensive w.r.t to the data)
- Compute **view-based rewriting** and answer it on the view-graph (polynomial w.r.t. to data)
Will go with this here.

View-Based Rewriting

[Calvanese, DeGiacomo, Lenzerini, Vardi
PODS 1999]

$Q' = v^*$:

All words on Ω whose substitution is contained in Q.



Unnecessary Recursion

$$Q' = v^*$$

But why not just:

$$Q'' = v$$

Surely: $Q' \neq Q''$

...as languages on Ω .

However, they are equivalent should we “substitute” v by V ,
and have languages on Δ .

Hence, we should rather talk about Ω/Δ equivalence.

Unnecessary Recursion – Another Example

$$Q = R^*R^k$$

$$V = R^+$$

$$Q' = (v^k)^+$$

Recall, it's all words on Ω whose substitution is contained in Q

but...

$$Q'' = v^k$$

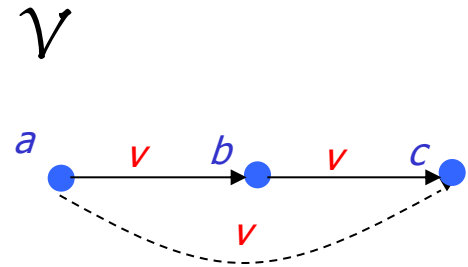
which is clearly better.

Possible Databases and Valid View-Graphs

- $poss(\mathcal{V})$: Set of all databases from which a given view-graph \mathcal{V} might have been generated.

- Valid \mathcal{V} : when $Poss(\mathcal{V})$ not empty

- Under **exact view assumption**, not all view graphs are valid.
 - E.g., consider $V=R^*$ and



$$poss(\mathcal{V}) = \emptyset.$$

because \mathcal{V} “misses” a v-edge from a to c .

Characterization Theorem

Theorem. *Let Q_1 and Q_2 be queries on Ω .
Under exact view assumption,*

$$Q_1 \equiv_{\Omega/\Delta} Q_2$$

iff

for each valid view graph \mathcal{V}

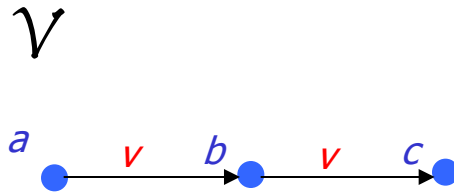
$$ans(Q_1, \mathcal{V}) = ans(Q_2, \mathcal{V}).$$

Corollary. Minimize as much as possible a query on Ω (i.e. a view-based rewriting) without losing query-power as long as Ω/Δ -equivalence is preserved.

...and Ω/Δ -equivalence is algebraically weaker than Ω -equivalence.

Sound Views

- Previous theorem doesn't hold for sound views.
- **E.g.**, consider $V=R^*$, which is Ω/Δ -equivalent with V^* , and



For \mathcal{V} , we have that $ans(v^*, \mathcal{V}) \neq ans(v, \mathcal{V})$.

- Clearly, the answer of V will be equal to the answer of V^* on each database on Δ ,
...but because the view is assumed to be sound we cannot enforce \mathcal{V} to have an additional v -edge from a to c .

Two Notions of Boundedness

- Q_k set of all Ω -words in Q , of length not more than k .

Definition

1. Q is k -bounded iff $Q_k \equiv_{\Omega/\Delta} Q$.
2. Q is finitely bounded iff $\exists k \in \mathbb{N}$, such that Q is k -bounded.

Theorems

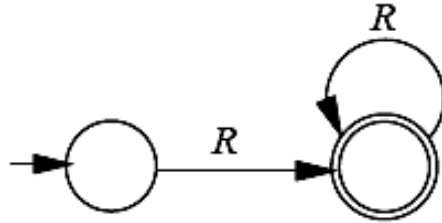
- *k*-boundedness is *PSPACE*-complete w.r.t. the size of the query.
- Finite boundedness can be decided in *EXPTIME* w.r.t. the size of the query.

Limitedness Problem in Distance Automata

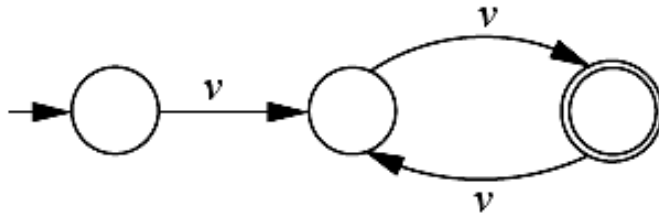
- Let A be an ε -free **weighted** automaton (known as *distance automata*.)
 - $d_A(p,w,q) =$
 $\inf\{\text{weight}(\pi) : \pi \text{ is a path spelling } w, \text{ from } p \text{ to } q \text{ in } A\}$
 - $d(A) =$
 $\sup\{d_A(s,w,f) : s \text{ start state, } f \text{ final state}\}$
 - A is limited in distance iff $d(A) < \infty$
- Limitedness Problem [Hashiguchi 82]:
Is a given distance automaton A limited in distance?

Reduction (I)

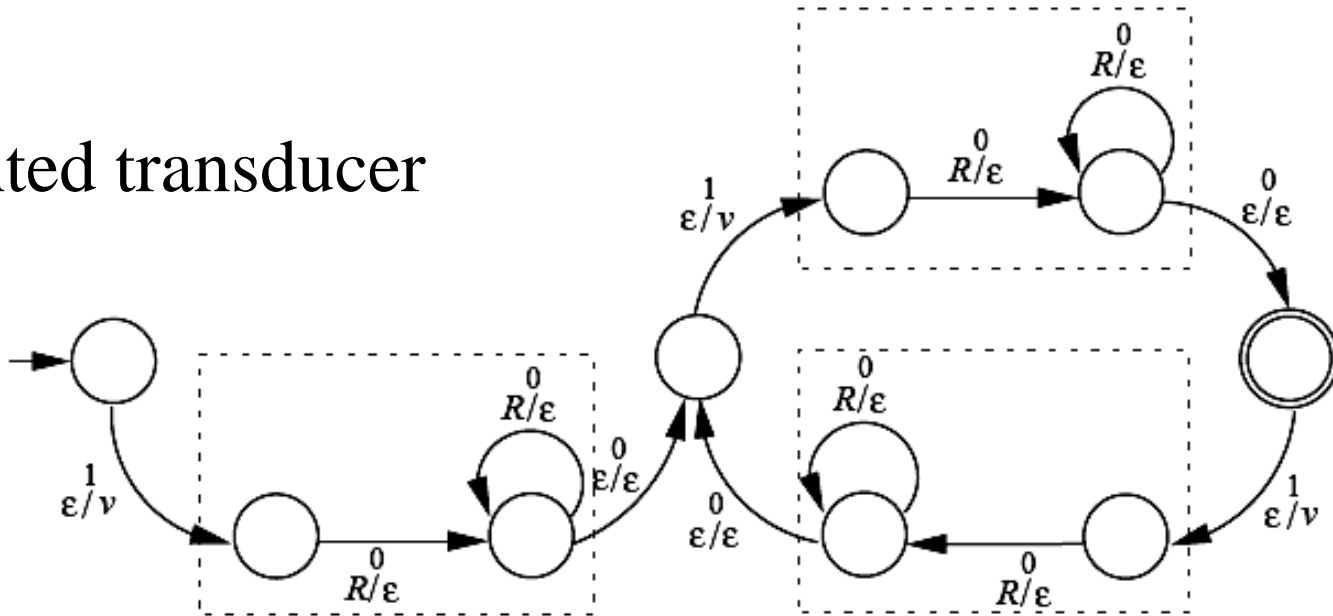
View definition



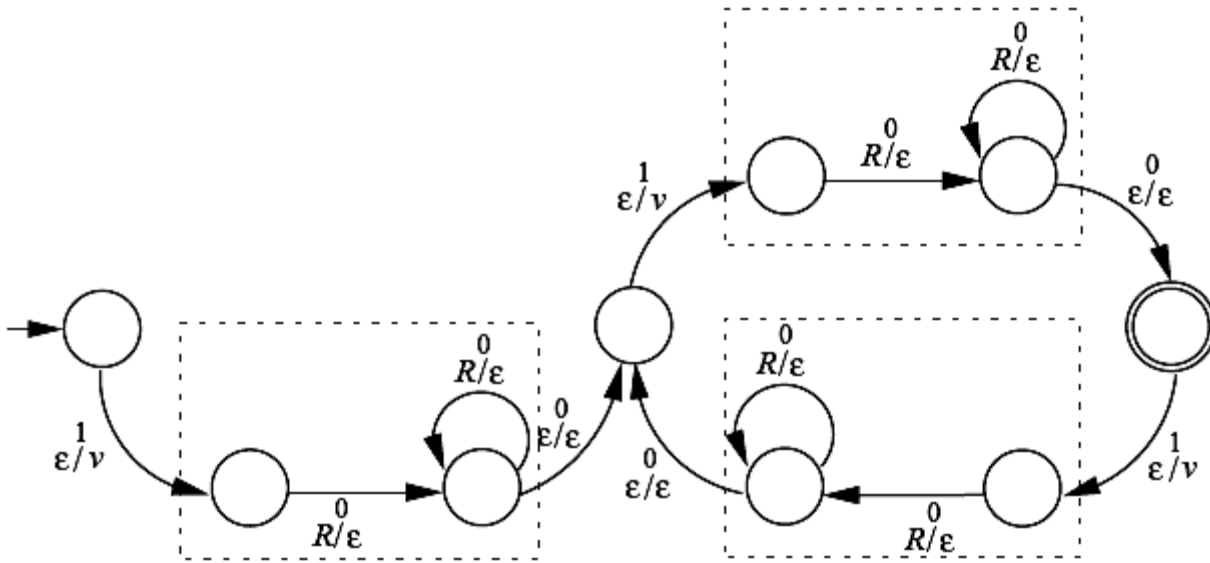
View-based
Rewriting



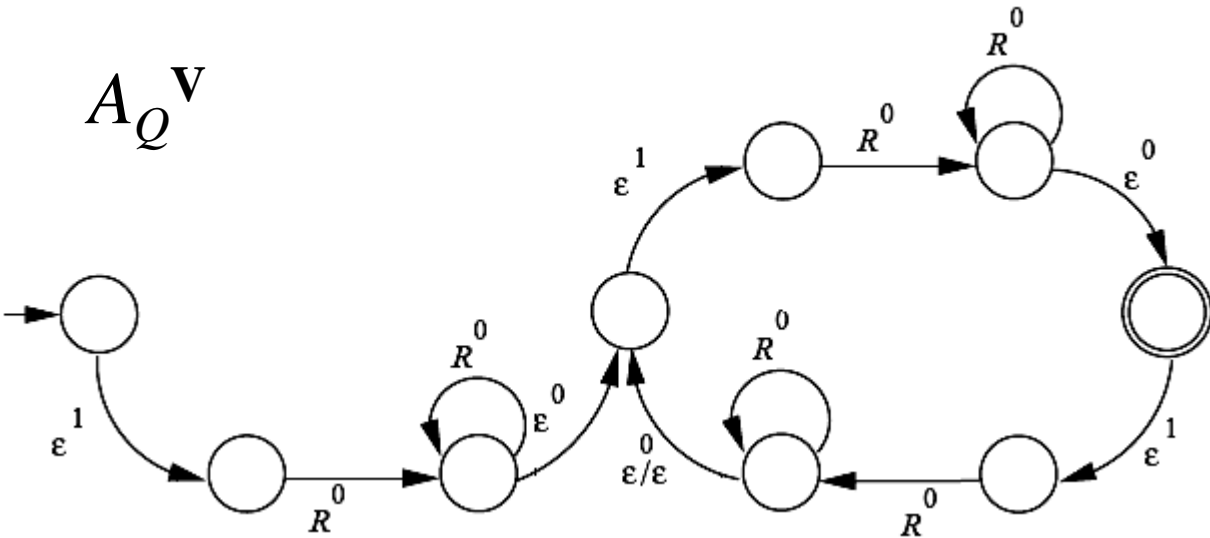
Weighted transducer



Reduction (I)



A_Q^V



Drop output
and obtain a
weighted
automaton.

Do epsilon
removal.

Characterization

- **Our characterization:**

Q is bounded iff A_Q^V is limited in distance.

References

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