

# CSc 360

## Operating Systems

### Process Synchronization

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## Review

- Race condition
  - concurrent access to shared data: inconsistency
    - dependent on the order of execution at CPU level!
- Critical section
  - where shared data are accessed
- Mutual exclusion
  - `pthread_mutex_lock()`, `pthread_mutex_unlock()`
  - how is mutual exclusion implemented indeed?

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## Properties of “solutions”

- Mutual exclusion
  - no more than one process in the critical section
- Making process
  - if no process in the critical section, one can in
- Bounded waiting
  - for processes that want to get in the critical section, their waiting time is bounded

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## Problem formulation

- Only 2 processes,  $P_0$  and  $P_1$
- General structure of  $P_i$  (other process  $P_j$ )

```
do {  
    entry section  
    critical section  
    exit section  
    reminder section  
} while (1);
```
- Processes may **share** some common variables to synchronize their actions
  - do not get into loop!

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## Algorithm 1

- Shared variables
  - int turn;  
initially **turn = 0**
  - $\text{turn} == i \vdash P_i$  can enter its critical section
- Process  $P_i$ 

```
do {  
    while (turn != i) ;  
    critical section  
    turn = j;  
    reminder section  
} while (1);
```
- Fate on other's hands: any problems?

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## Algorithm 2

- Shared variables
  - boolean flag[2];  
initially **flag [0] = flag [1] = false.**
  - $\text{flag [i]} = \text{true} \vdash P_i$  ready to enter its critical section
- Process  $P_i$ 

```
do {  
    flag[i] := true;  
    while (flag[j]) ;  
    critical section  
    flag [i] = false;  
    remainder section  
} while (1);
```
- Fight for access: any problems?

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## Dekker's solution

- Combined shared variables of Algos 1 and 2
- Process  $P_i$

```
while (true) {  
    flag[i] = true;  
    while (flag[j]) {  
        if (turn == j) {  
            flag[i] = false;  
            while (turn == j) {}  
            flag[i] = true;  
        }  
        /* critical section */  
        turn = j;  
        flag[i] = false;  
    }  
}
```

- Be polite: meet all three requirements; solve the critical-section problem for **two** processes

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## Peterson's solution

- A simpler solution
  - combined shared variables of Algorithms 1 and 2

- Process  $P_i$

```
do {  
    flag [i] := true;  
    turn = j;  
    while (flag [j] and turn == j) ;  
    /* critical section */  
    flag [i] = false;  
    /* remainder section */  
} while (1);
```

- Meet all three requirements; solve the critical-section problem for **two** processes

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## This lecture

- Process synchronization
  - software solution for 2 processes
    - Peterson's solution
- Explore further
  - Lamport's bakery algorithm
    - for  $n$  processes
    - it's time to google!

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## Next lecture

- Process synchronization
  - other alternatives (read OSC7Ch6)

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