The initial dictionary:

 $z = 0 + 1 \times 1 + 2 \times 2 + 3 \times 3 + 4 \times 4$

The final dictionary:

- X1 = a +3 X3 +4 X4 -2/3 X5 +1 X7 X6 = b -2 X3 -2 X4 + 0 X5 +0 X7 X2 = c -3 X3 -4 X4 +1/3 X5 -1 X7X8 = d -6 X3 -8 X4 +2/3 X5 +0 X7
- z = e + 0 X3 + 0 X4 + 0 X5 1 X7

- 1. What matrix A in the computer
 - corresponds to the initial dictionary?
 - 2. What is the basis matrix B for the final dictionary?
 - 3. What matrix A corresponds to the final dictionary?
- 4. How can you determine B⁻¹ from the final dictionary?
- 5. Solve for a, b, c, d, and e.

Announcements

The midterm is in class on Friday Oct. 10. A midterm study aid and some old midterms have been posted.

No office hours on Friday Oct. 10.

Special midterm tutorial: Thursday Oct. 9, 6pm, ECS 108. Bring any questions you have about anything in the class. I can go through solutions for assignment questions. Student: Solves primal or dual problem whichever is easiest.

Primal: 9 variables, and 100 equations. Dual: 100 variables, and 9 equations.

Text: claims that in practice, it is usually best to choose the problem with the least rows.

Student reads both primal and dual solutions from last dictionary.

Certificate: x* and y*, the optimal primal and dual solutions.

Supervisor: Has certificate plus primal and dual problems.

- 1. Check that x^* is primal feasible.
- 2. Check that y* is dual feasible.

These checks guarantee optimality.

Easier usually than solving LP problem.

The problems: The primal problem:

Maximize - 3 X₁ - 2 X₂

subject to

The dual problem in standard form:

Maximize $3Y_1 + 5Y_2 + 1Y_3 + 0Y_4$

subject to

 $Y_1, Y_2, Y_3, Y_4 \ge 0$

 $X_1, X_2 \ge 0$

The student notices that the primal has no initial feasible basis so cannot be handled by the code written for the project. So the student solves the dual instead:

The initial dictionary: Y5= 3 + 1 Y1 - 2 Y2 + 0 Y3 - 1 Y4 Y6= 2 - 1 Y1 - 1 Y2 - 2 Y3 - 4 Y4z = 0 + 3 Y1 + 5 Y2 + 1 Y3 + 0 Y4 After 2 pivots: Y2= 1.67 -0.67 Y3 -1.67 Y4 -0.33 Y5 -0.33 Y6 Y1= 0.33 -1.33 Y3 -2.33 Y4 +0.33 Y5 -0.67 Y6 z = 9.33 -6.33 Y3 -15.33 Y4 -0.67 Y5 -3.67 Y6

The student guesses that 0.33 really means 1/3 and 0.67 is 2/3. So the certificate is:

$$Y_1 = 1/3$$
, $Y_2 = 5/3$, $Y_3 = 0$, $Y_4 = 0$

 $X_1 = -1$ (coeff. of Y5)= 2/3 $X_2 = -1$ (coeff. of Y6)= 3 2/3 = 11/3 The primal $X_1 = 2/3$ $X_2 = 11/3$ problem: Check for primal Maximize feasibility, the red $-3X_1 - 2X_2$ subject to equations are tight: $1 X_1 - 1 X_2 \le -3 \quad 1(2/3) - 1(11/3) = -9/3$ ≤ -3 $-2 X_1 - 1 X_2 \le -5 -2(2/3) - 1(11/3) = -15/3$ ≤ -5 $-0 X_1 -2 X_2 \le -1 \quad 0(2/3) - 2(11/3) = -22/3$ ≤ -1 $-1 X_1 -4 X_2 \le 0 -1(2/3) - 4(11/3) = -46/3$ ≤ 0 $2/3, 11/3 \ge 0$ $X_1, X_2 \ge 0$ 8 Check $Y_1 = 1/3$, $Y_2 = 5/3$, $Y_3 = 0$, $Y_4 = 0$ for dual feasibility:

 $\begin{array}{rrrr} -1Y_1 & +2Y_2 & +0Y_3 & +1Y_4 \leq 3 \\ 1Y_1 & +1Y_2 & +2Y_3 & +4Y_4 \leq 2 \\ Y_1, & Y_2, & Y_3, & Y_4 \geq 0 \end{array}$

 $1/3, 5/3, 0, 0 \ge 0$

Check the objective function values:

The primal problem: Maximize

 $X_1 = 2/3$ $X_2 = 11/3$ The dual (not in standard form): Minimize $-3Y_1 - 5Y_2 - 1Y_3 + 0Y_4$ $Y_1 = 1/3, Y_2 = 5/3,$ $Y_3 = 0, Y_4 = 0$

-6/3-22/3 = -28/3 -1 -25/3 -0+ 0= -28/3

Conclusion:

•(2/3, 11/3) is an optimal primal solution. •(1/3, 5/3, 0, 0) an optimal dual solution. Complementary slackness allows us to find a dual solution from a primal one.

What can we conclude by looking at the equations which are not tight?

The slacks are then non-zero and hence must be in the basis and so they have a (implicit) zero coefficient in the z row.

So the corresponding y variables must be 0.

Conclusion: if $x_{n+i} \neq 0$ then $y_i = 0$.

The red equations are tight: Slack 1(2/3) - 1(11/3) = -9/3 ≤ -3 X₃ -2(2/3)-1(11/3) = -15/3 ≤ -5 X_4 0(2/3) - 2(11/3) = -22/3 ≤ -1 **X**₅ -1(2/3)-4(11/3) = -46/3 ≤ 0 X_6 0.33 X3 + 0.33 X4 X1 = 0.67 -X2 = 3.67 + 0.67 X3 +0.33 X4 0.67 X4 X5 = 6.33 + 1.33 X3 +X6 = 15.33 + 2.33 X3 +1.67 X4 $z = -9.33 - 0.33 \times 3 - 1.67 \times 4$

Conclusion: $y_3 = y_4 = 0$.

What can we conclude by looking at the x_i 's that are non-zero, i = 1, 2, ..., n? $x_i = -1^*$ (coefficient of the ith slack y_{m+i} for the dual problem's last dictionary).

So if x_i is non-zero, y_{m+i} cannot be in the basis in the last dual dictionary since otherwise it has an implicit 0 coefficient. So $y_{m+i} = 0$ and equation i of the dual hence must be tight.

Conclusion: if x_i is non-zero, equation i of the dual must be tight.

The initial dictionary: Y5= 3 + 1 Y1 - 2 Y2 + 0 Y3 - 1 Y4 Y6= 2 - 1 Y1 - 1 Y2 - 2 Y3 - 4 Y4z = 0 + 3 Y1 + 5 Y2 + 1 Y3 + 0 Y4

After 2 pivots: Y2= 1.67 -0.67 Y3 -1.67 Y4 -0.33 Y5 -0.33 Y6 Y1= 0.33 -1.33 Y3 -2.33 Y4 +0.33 Y5 -0.67 Y6 z = 9.33 -6.33 Y3 -15.33 Y4 -0.67 Y5 -3.67 Y6 X1= 2/3 [0.67] X2= 14/3 [3.67]

X1 = 0.67 - 0.33 X3 + 0.33 X4 X2 = 3.67 + 0.67 X3 + 0.33 X4 X5 = 6.33 + 1.33 X3 + 0.67 X4 X6 = 15.33 + 2.33 X3 + 1.67 X4z = -9.33 - 0.33 X3 - 1.67 X4

Since x_1 and x_2 are non-zero, both dual equations must be tight:

 Solving this:

y₃=**y**₄=0.

Add them together: 3 Y_2 = 5 so Y_2 = 5/3

$$Y_1 + Y_2 = 2$$
 so $Y_1 = 1/3$

The idea for complementary slackness: 1. If $x_{n+i} \neq 0$ for some i = 1, 2, ..., m, then x_{n+i} is in the basis and hence has an implicit 0 coefficient in the z row of the last dictionary and this implies that $y_i=0$.

2. If $x_i \neq 0$ for some i= 1, 2, ..., n, then the ith dual equation is tight ($y_{m+i}=0$) because otherwise, if $y_{m+i} \neq 0$, it is in the basis of the last dual dictionary and hence would have an implicit 0 coefficient in the z row of the last dual dictionary and this would imply $x_i=0$. In other words:

- 1. If equation i of the primal is not tight, $y_i=0$.
- 2. If $x_i \neq 0$, i= 1, 2, ..., n the ith dual equation is tight.

Complementary Slackness Theorem (5.2): x' = feasible primal solution y' = feasible dual solution Necessary and sufficient conditions for simultaneous optimality of x' and y' are 1. For all i=1, 2, ..., m, either $(a_{i1} * x_1' + a_{i2} * x_2' + ... + a_{in} * x_n') = b_i$ or $y_i' = 0$ (or both).

2. For all i=1, 2, ..., n, either $(a_{1j} * y_1' + a_{2j} * y_2' + ... + a_{mj} * y_m') = c_i$ or $x_i' = 0$ (or both). We have already argued that these conditions are necessary for optimality.

Why are they sufficient?