My grad student was doing research for me and printed the output for a problem but unfortunately lost the last page of the output that had the final z row on it. I want to know the solution to the dual problem. Which variables from the dual problem must be 0? Explain why.

 Summary of complementary slackness:

- 1. If $x_i \neq 0$, i= 1, 2, ..., n the ith dual equation is tight.
- 2. If equation i of the primal is not tight, $y_i=0$.

The problem from the previous slide was: Maximize 1 X1 +2 X2 +1 X3 +2 X4 subject to

- $1 X1 + 0 X2 + 1 X3 + 0 X4 \le 35$
- $3 X1 3 X2 + 5 X3 + 1 X4 \le 5$

X1, X2, X3, X4 \geq 0

The solution had X1= 0, X2= 30, X3= 0, X4= 5

Finish solving for the dual solution using complementary slackness.

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Checking our algebra with the last dictionary:

After 5 pivots: X5= 35 - 1.0 X1 - 1.0 X3 + 0.0 X6 + 0.0 X7 X2= 30 - 2.0 X1 + 0.0 X3 - 1.0 X6 + 0.0 X7 X4= 5 + 0.5 X1 - 2.5 X3 + 0.5 X6 - 0.5 X7 X8= 90 - 9.5 X1 - 2.5 X3 - 3.5 X6 + 0.5 X7z = 70 - 2.0 X1 - 4.0 X3 - 1.0 X6 - 1.0 X7

Complementary Slackness Theorem (5.2): x' = feasible primal solution y' = feasible dual solution Necessary and sufficient conditions for simultaneous optimality of x' and y' are 1. For all i=1, 2, ..., m, either $(a_{i1} * x_1' + a_{i2} * x_2' + ... + a_{in} * x_n') = b_i$ or $y_i' = 0$ (or both).

2. For all i=1, 2, ..., n, either $(a_{1j} * y_1' + a_{2j} * y_2' + ... + a_{mj} * y_m') = c_i$ or $x_i' = 0$ (or both).

Recipe for Using this Theorem

Given: x' which is a feasible solution. Question: Is x' an optimal solution?

Procedure:

1. First consider each x_j' (j=1, 2, ..., n) such that x_j' is NOT 0. Write down the equation of the dual that corresponds to the coefficients of x_j in the primal: $(a_{1j} y_1 + a_{2j} y_2 + ... + a_{mj} y_m) = c_j$

Next consider each equation i of the primal problem (i=1, 2, 3, ..., m). If the ith equation is NOT tight (there is some slack), write down y_i= 0.

3. Solve these equations that you get for y. If there is a unique solution continue. If not, abort.

4. Test y to see if it is dual feasible. Yes- x' is optimal. No- x' is not optimal.

When does the system of equations have a unique solution?

Theorem 5.4 in text: when x' is a nondegenerate basic feasible solution.

Nondegenerate: no basic variables have value 0.

The problem:

Maximize 5 X_1 + 4 X_2 + 3 X_3 subject to

 $X_1, X_2, X_3 \ge 0$

The second last dictionary: u= (2.5, 0, 0)

X1 = 2.5 - 1.5 X2 - 0.5 X3 - 0.5 X4 X5 = 1 + 5 X2 + 0 X3 + 2 X4X6 = 0.5 + 0.5 X2 - 0.5 X3 + 1.5 X4

z = 12.5 - 3.5 X2 + 0.5 X3 - 2.5 X4

Check this using complementary slackness.

u=(<mark>2.5</mark>, 0, 0) Maximize

 $5 X_1 + 4 X_2 + 3 X_3$ Constraints:

 $2 X_1 + 3 X_2 + 1 X_3 \leq 5$ $4 X_1 + 1 X_2 + 2 X_3 \leq 11$ $3 X_1 + 4 X_2 + 2 X_3 \leq 8$ 1. First consider each X_i' such that X_i' is NOT 0. Write down the equation of the dual that corresponds to the coefficients of X_i in the primal: $X_1 \neq 0$: 2 $Y_1 + 4 Y_2 + 3 Y_3 = 5$

2. Next consider each equation i of the primal problem If the ith equation is NOT tight (there is some slack), write down $Y_i = 0$.

2(2.5) + 3(0) + 1(0) = 5 = 5 TIGHT 4(2.5) + 1(0) + 2(0) = 10 < 11 Y₂=0 3(2.5) + 4(0) + 2(0) = 7.5 < 8 Y₃=0

Solve for y: $2 Y_1 + 4 Y_2 + 3 Y_3 = 5$ $Y_2 = 0$ $Y_3 = 0$

 $y_1 = 5/2, y_2 = 0, y_3 = 0.$

The problem:

Maximize 5 X_1 + 4 X_2 + 3 X_3 subject to

What is the dual? Check y1= 5/2, y2=0, y3=0 for dual feasibility. The last dictionary: v= (2, 0, 1)

- X1 = 2 2 X2 2 X4 + 1 X6X5 = 1 + 5 X2 + 2 X4 + 0 X6
- X3 = 1 + 1 X2 + 3 X4 2 X6
- z = 13 3 X2 1 X4 1 X6

Check this using complementary slackness.

1. Write down dual equations for non-zero X_i's: v= (2, 0, 1) Maximize

 $5 X_1 + 4 X_2 + 3 X_3$ Constraints:

 2. Next consider each equation i of the primal problem If the ith equation is NOT tight (there is some slack), write down $Y_i = 0$. v = (2, 0, 1)Constraints:

2(2) + 3(0) + 1(1) = 5 = 5 TIGHT 4(2) + 1(0) + 2(1) = 10 < 11 Y₂=0 3(2) + 4(0) + 2(1) = 8 = 8 TIGHT 3. Solve for Y.

Solution: (1, 0, 1)

Test y for dual feasibility.

We have already argued that these conditions are necessary for optimality.

Why are they sufficient?

Complementary Slackness Theorem (5.2): x' = feasible primal solution y' = feasible dual solution Necessary and sufficient conditions for simultaneous optimality of x' and y' are 1. For all i=1, 2, ..., m, either $(a_{i1} * x_1' + a_{i2} * x_2' + ... + a_{in} * x_n') = b_i$ or $y_i' = 0$ (or both).

2. For all i=1, 2, ..., n, either $(a_{1j} * y_1' + a_{2j} * y_2' + ... + a_{mj} * y_m') = c_i$ or $x_i' = 0$ (or both). Earlier we showed that for feasible primal and dual solutions:

 $C_1 X_1 + C_2 X_2 + \dots + C_n X_n \le S =$ $(a_{11} y_1 + a_{21} y_2 + \ldots + a_{m1} y_m) x_1 +$ $(a_{12} y_1 + a_{22} y_2 + \ldots + a_{m2} y_m)x_2 +$... + $(a_{1n} y_1 + a_{2n} y_2 + \dots + a_{mn} y_m) x_n$ $(a_{11} x_1 + a_{12} x_2 + \ldots + a_{1n} x_n)y_1 +$ $(a_{21} x_1 + a_{22} x_2 + \dots + a_{2n} x_n)y_2 +$... + $(a_{m1} x_1 + a_{m2} x_2 + \dots + a_{mn} x_n) y_m$ $\leq b_1 y_1 + b_2 y_2 + \dots + b_m y_m$

In a final dictionary: m basic variables. Of these, assume b of them are from x_1 , ..., x_n and the remaining m-b are slacks. If the solution is not degenerate then we get b equations from having the non-zero values from x_1, \dots, x_n and m-b equations that are not tight.

This gives a square (b by b) system to solve.

Complementary Slackness Theorem (5.2): x' = feasible primal solution y' = feasible dual solution Necessary and sufficient conditions for simultaneous optimality of x' and y' are 1. For all i=1, 2, ..., m, either $(a_{i1} * x_1' + a_{i2} * x_2' + ... + a_{in} * x_n') = b_i$ or $y_i' = 0$ (or both). Problem is the 2. For all i=1, 2, ..., n, either "or $(a_{1j} * y_1' + a_{2j} * y_2' + ... + a_{mj} * y_m') = c_i$ or $x_i' = 0$ (or both). both" parts.